


CS 421 Lecture 12

- ▶ **Compilation static languages, continued**
 - ▶ Compiling in context
 - ▶ Assignment
 - ▶ Break and ~~labeled~~ statements
 - ▶ Short-circuit evaluation of boolean expressions
 - ▶ Switch statements
 - ▶ Arrays
 - ▶ Code optimization
- ▶ Friday's class: dynamic languages – ~~code generation~~, garbage collection, reflection

Notation

- ▶ $[S]$ = compiled code for S
- ▶ $[e]$ = compiled code for e
- ▶ Use subscripts on brackets for additional arguments, e.g. $[S]_L$ is compiled code for S , assuming S occurs within a switch statements labeled L .

$$\text{compile}(S) = \underline{\underline{\underline{\quad}}}$$


$$\rightarrow \text{compile}(S, L) = \underline{\underline{\underline{\quad}}}$$

Assignment statements

- ▶ Old scheme: $[x=e] = \text{let } (l,t) = [e] \text{ in } l; x=t.$
- ▶ Can give poor results: $[x=3] = t=3; x=t$
 $[x=x+1] = t1=1; t2=x+t1; x=t2$
- ▶ Compile expressions in context of target location:
 $[e]_x =$ code to calculate value of e and store it in x . $[e]_x$: instruction list

▶ $[x=e] = [e]_x$

▶ $[n]_x = "x=n"$

▶ $[y]_x = "x=y"$, if y a different variable from x ; ϵ , otherwise

▶ $[e1+e2]_x = \text{let } t = \text{new location in } [e1]_t; [e2]_x; x=t+x$

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$$[x = x + 1] = [x + 1]_x = \begin{matrix} [x]_t \\ [1]_x \\ x = t + x \end{matrix} \left. \begin{matrix} t = x \\ x = 1 \\ t = t + x \end{matrix} \right\}$$

$$[x = 1 + x] = [1 + x]_x = \begin{matrix} [1]_t \\ [x]_x \\ x = t + x \end{matrix} \left. \begin{matrix} t = 1 \\ x = t + x \end{matrix} \right\}$$

compile (break, L_b, L_c)

Same as [S]
for non-break stmts

break statements

- ▶ break statement breaks from one level of switch or while. Cannot translate "break" without knowing context.
- ▶ [S]_L = code for statement S, given that S occurs inside a switch or while statement, and L is the label just after that enclosing statement.

[S]_{L_b, L_c}

[break]_{L_b, L_c} = JUMP L_b

[continue]_{L_b, L_c} =
JUMP L_c

[while e do S] = JUMP L₂
 L₁: [S]_{L₃, L₂}
 L₂: [e]

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JUMP t, L₁, L₃

L₃:

Boolean expressions

$x \neq 0$ & y/x ...
 $x := null$ & $x.t :=$...
 $x < n$ & $A[x] =$...

▶ Current scheme: boolean expressions evaluated like any other, placing value in a temporary location:

$[e1 < e2] = \text{let } (l_1, t1) = [e1], (l_2, t2) = [e2], t = \text{newloc}()$
in $(l_1; l_2; t = t1 < t2, t)$

$[e1 \ \&\& \ e2] = \text{let } (l_1, t1) = [e1]$
 $(l_2, t2) = [e2]$
in $(l_1; l_2; t = t1 \ \&\& \ t2, t)$

$[\text{if } e \text{ then } S1 \ \text{else } S2] = \text{let } (l, t) = [e]$
in $(l; \text{CJUMP } t \ L1 \ L2; \dots)$

$\{ \text{if } (x < y \ \&\& \ y < z)$
then ... $\}$

$=$
 $t1 = x < y$
 $t2 = y < z$
 $t3 = t1 \ \&\& \ t2$
 $\text{CJUMP } t3, L1, L2$
 \vdots

What's wrong?

Boolean expressions w/ short-circuit evaluation

► Improved scheme:

$[e1 \ \&\& \ e2] = \text{let } t = \text{newlocation}()$

if $(x < y \ \&\& \ y < z)$ then

$t = x < y$
CJUMP $t, L1, L2$ ^{L3}

L1: $t = y < z$

L2: CJUMP $t, L2, L3$
}

$I_1 = [e1]_t$

$I_2 = [e2]_t$

$L1, L2 = \text{newlabel}()$

in $(I_1$

CJUMP $t, L1, L2$

L1: I_2

L2:

t contains value of e_1 // e_2 and e_2 is evaluated only if needed

• What's wrong now?

Compiling boolean expressions in context

- ▶ Get better code if boolean expression can jump to correct label as soon as possible
- ▶ $[e]_{Lt,Lf}$ = code that calculates e and jumps to Lt if it is true, Lf if it is false. The code does not save the value anywhere.

▶ $[true]_{Lt,Lf} = \text{JUMP } Lt$

$$[e_1 < e_2]_{Lt,Lf} = \text{let } (I_1, t_1) = [e_1] \\ (I_2, t_2) = [e_2]$$

in

I_1
 I_2

$t = t_1 < t_2$

$\text{cJUMP } t, Lt, Lf$

Compiling boolean expressions in context

▶ $[e_1 \ \&\& \ e_2]_{L_t, L_f} = [e_1]_{L_1, L_f}$
 $L_1: [e_2]_{L_t, L_f}$

$[if \ e \ then \ S_1 \ else \ S_2]$
 $= [e]_{L_1, L_2}$
 $L_1: [S_1]$
 JUMP L_3
 $L_2: [S_2]$
 $L_3:$

$[while \ e \ do \ S] =$
 JUMP L_2
 $L_1: [S]$
 $L_2: [e]_{L_1, L_3}$

$L_3:$

$[if \ (x < y \ \&\& \ y < z) \ then \ \dots]$
 $= [x < y \ \&\& \ y < z]_{L_1, L_2}$
 $= [x < y]_{L_4, L_2}$
 $L_4: [y < z]_{L_1, L_2}$

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$[!e]_{L_t, L_f} = [e]_{L_f, L_t}$

$[e_1 \ || \ e_2]_{L_t, L_f} = [e_1]_{L_t, L_1}$
 $L_1: [e_2]_{L_t, L_f}$

L3:

[if $(x < y \ \&\& \ y < z)$ then...]

= $[x < y \ \&\& \ y < z]_{L1, L2}$

= $[x < y]_{L4, L2}$

L4: $[y < z]_{L1, L2}$

= $t_1 = x < y$
CJUMP $t_1, L4, L2$

L4: $t_2 = y < z$
CJUMP $t_2, L1, L2$

L1: [S.]

⋮

good

Compiling switch statement

- ▶ Use "jump table" and address calculation

```
[ switch (e) {  
  case 0: S0  
          break  
  case 1: S1  
          break  
  ⋮  
  } ]
```

=

```
let (I, t) = [e]  
m I  
σ = t * 4  
l = table + σ  
JUMPIVD l  
L0: [S0]  
    JUMP L  
    ⋮  
L:
```

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table: L0, L1, L2, ...

Compiling object references

- ▶ In expression $e.t$:
 - ▶ Type of e is known; call its class C
 - ▶ Location of field t within C is known; say its offset is o
 - ▶ $[e]$ will produce (l, t) , where t contains pointer to object
- ▶ $[e.t] = \text{let } (l, t) = [e]$
 $t1 = \text{newlocation}()$
 in $(l; t1 = t + o, t1)$
- ▶ Method calls $e.t(\dots)$ more complicated – will discuss in a couple of weeks

*address of e.x
To get value, add:
t2 = LOADIND t1*

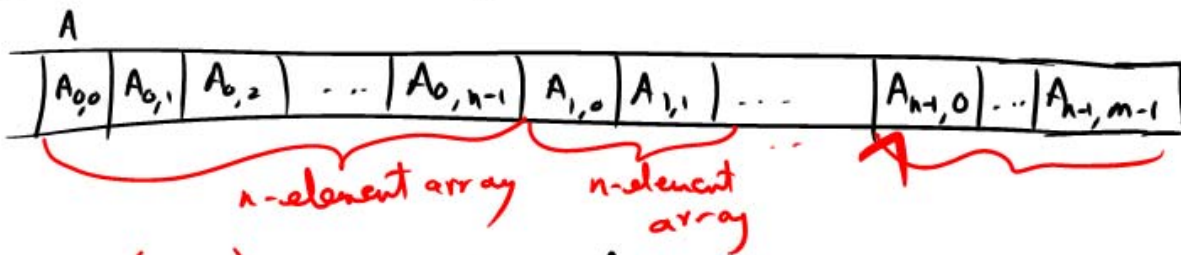
Compiling array references

- ▶ Simple rule: If A has elements of type T , and if elements of type T occupy n bytes, then address of $A[i]$ is address of $A + i*n$.
- ▶ $[A[e]] = \text{let } (l, t) = [e]$
in $(l$
 $t1 = \&A$
 $t2 = t*w$ (w size of A 's elements)
 $t3 = t1+t2$
 $t4 = \text{LOADIND } t3, \quad t4)$

Compiling array references

► Idea extends to multi-dimensional arrays.

Traditional 2-d arrays (C, FORTRAN)



$$[(A[i])[j]] = t_1 = \&A$$

$$t_2 = i * (4 * n)$$

$$t_3 = t_1 + t_2$$

width of elements of A

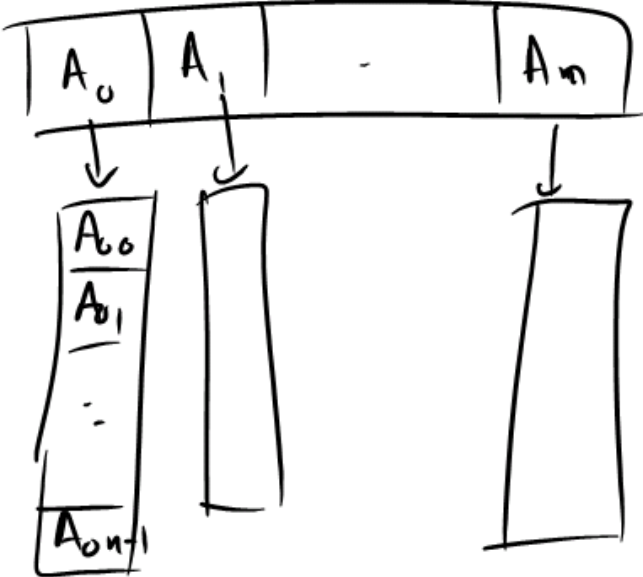
$$t_4 = j * 4$$

$$t_5 = t_3 + t_4$$

$$t_6 = \text{LOADIND } t_5$$

for Java, LOADIND t_3 for location of array - also, use 4 instead of $4 * n$

Jawa 2-d arrays



Machine-independent optimizations

- ▶ Machine-independent optimization = optimizations that can be done at the level of IR – i.e. does not depend upon features of target machine such as registers, pipeline, special instructions
- ▶ E.g. “loop-invariant code motion”:

```
int A[100][100]
```

```
while (j < n) {  
    x = x + A[i][j]  
    j++;  
}
```

```
t1 = &A  
t2 = i*100  
t3 = t2+j  
t4 = t3*4  
t5 = t1+t4  
t6 = LOADIND t5  
x = x+t6  
j = j+1
```

*move to
before loop*

Machine-dependent optimizations

- ▶ Machine-dependent optimization = optimizations that exploit features of target machine such as registers, pipeline, special instructions
 - ▶ Register allocation
 - ▶ Instruction selection
 - ▶ Instruction scheduling

